

TROLLEY DESIGN

The trolley's central body is made of a square profile, which increases stiffness and robustness of the system. The electrically insulated wheels are provided by flanges. Permanent contact of the wheel flanges and running rail edge is provided by springs. A special apparatus having two degrees of the freedom in translation is at the central part of the longitudinal chord. It scans vertical and lateral rail versine.

The wheel surface treatment is executed in hard chromium. The trolley surface finish is yellow powder paint.

The arresting mechanism is controlled by rope & bowden and two levers on pushing rod when the trolley passes through the frog.

MEASURING PRINCIPLE

During the measuring run the following so called primary track values are scanned in space interval of 0,25 m:

- **gauge** (potentiometer transducer on the left wheel)
- **alignment** (lateral versine) of the right rail
- **top** (vertical versine) of the right rail
- **cant** (new, high reliable and precise inclinometer)
- **quasi-twist** on the twist base 0,9 m (option; it increases the precision of the final cant measuring)
- **track gradient** (option)
- **track distance** (odometer-optical encoder)
- **measuring speed**

ON BOARD COMPUTER

The real time processing of signals from the sensors is performed by rugged measuring computer (Android based system) with KrabDroid measuring software, whereby the following items are determined:

- reading and scanning of signals given above
- on-line processing of the signals:
 - anti-aliasing
 - smoothing of long wave part
 - optical signaling when the geometry data exceed the selectable thresholds
- display of numerical values of the geometry data
- entry of the geometry data into non-erasable storage of on-board computer at the distance 0,25 m (the measuring distance is limited by computer memory, typically 1000 km)
- entry of the information describing the track section to be measured
- entry selected events (e.g. mud spots in ballast, damaged sleepers etc.) with the exact position along the route

EVALUATION OF THE COLLECTED DATA BY KRAB 10 SOFTWARE

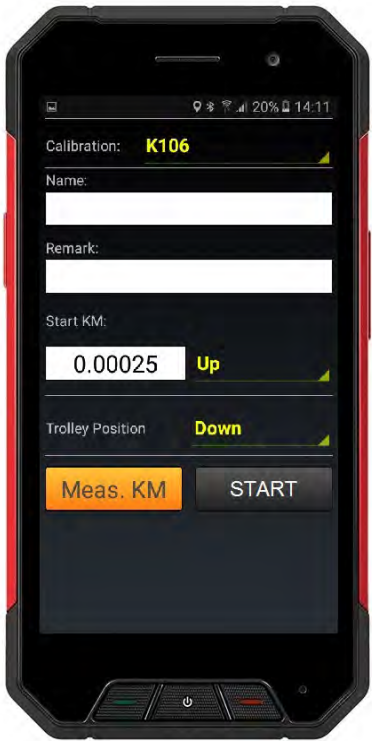
After the measuring, the collected raw geometry data are transferred from the measuring computer into any PC computer. Sophisticated assessment software computes so called actual geometry (with unit transfer function) in the waveband $\lambda=1\div 25$ m via FFT (Fast Fourier Transformation) technique. Thus the following items are available:

- actual alignment and level in waveband $\lambda = 1\div 25$ m
- separation of all geometric signals into long wave ($\lambda > 25$ m) and short wave ($\lambda < 25$ m) parts
- so called section evaluation - statistic evaluation of the track geometry based on standard deviation and quality index
- table of local defects, print out of geometrical lay and tables

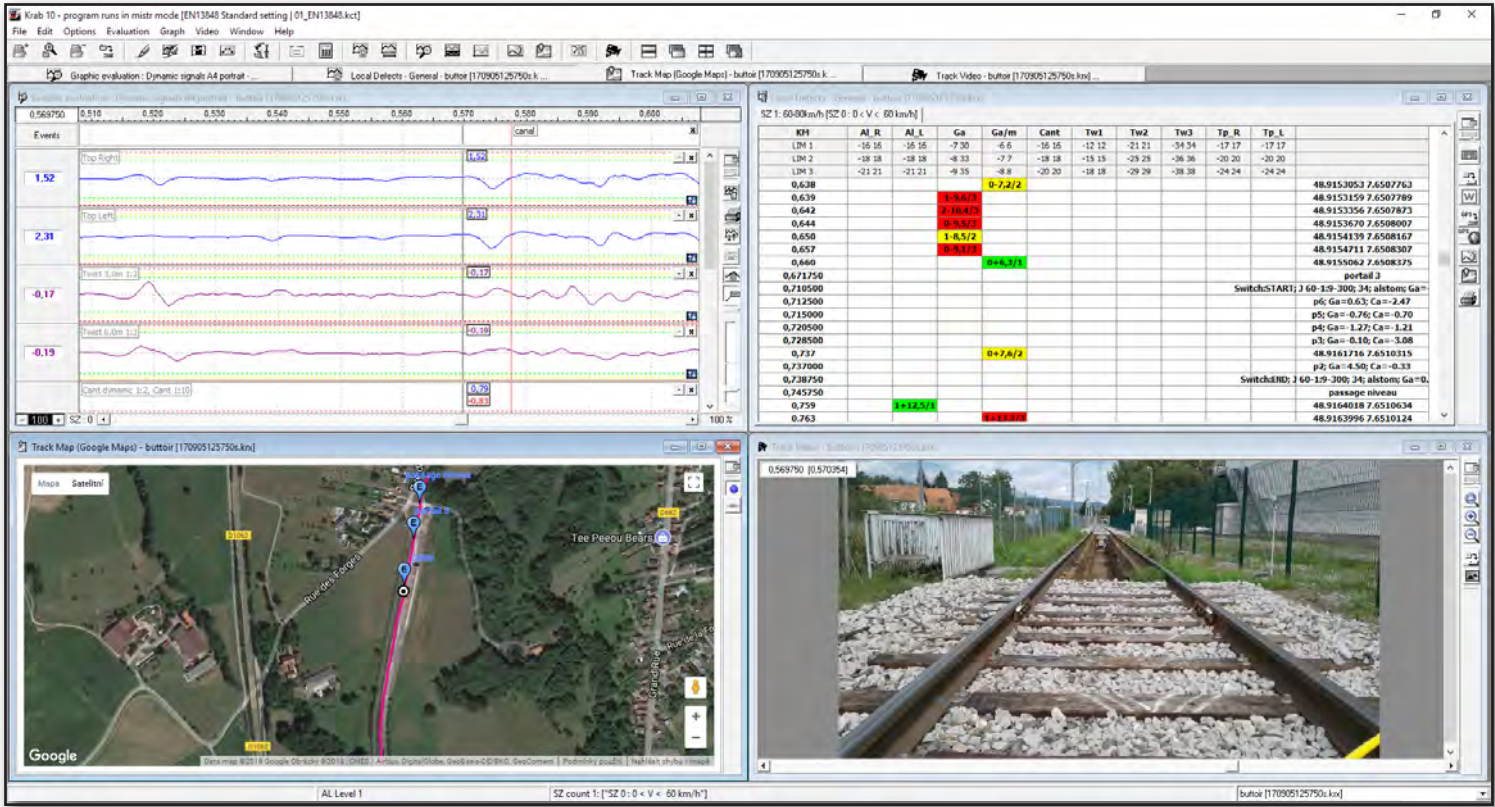
THE ACCURACY OF THE REPORTED GEOMETRY VALUES, SEE TAB.:

Geometric quantity to be measured	Resolution	Reproducibility 95% [mm]	Range ²⁾ [mm]
Vertical alignment - Top (waveband 1÷25 m)	0,1 mm	± 0,7	-15+12
Horizontal alignment (waveband 1÷25 m)	0,1 mm	± 1,0	± 25
Gauge	0,1 mm	± 0,45 ¹⁾	-15+40
Gauge variation (typically mm/2m)	0,1 mm	± 0,5	-
Cant (the relative value for twist calculation)	0,1 mm	± 0,7 ³⁾	-
Cant (the absolute value)	0,2 mm	± 1,0 ³⁾	± 180
Twist (any twist base)	0,1 mm	± 0,7/ℓ ³⁾	± 13
Speed	0,3 km/h	0,3 km/h	<15 km/h
Track distance	1,0 mm	1 ‰	No limits

¹⁾ excluding temperature effect, ²⁾ range of the primary values, ³⁾ arm of quasi-twist used



For easier transportation the trolley can be easily fold



The example of evaluation in Krab 10

THE BASIC TECHNICAL DATA:

Mass: 32 kg basic form

2,5 kg auxiliary twist arm

20 hours without battery charge

Working temperature: -5÷55 °C

KRAB S-Light can be used for switch point inspection as an option. The extra auxiliary rollers for flange groove width measuring have to be mounted on the basic trolley. Measuring program is provided by special part of switch point measuring. Extra analysis software SWITCH™ is available for off-line data manipulation, analysis and the Inspection Report print out. The switch point is understood as an integral part of the track. So the regular scanning of the track geometry values runs at background and important discrete location of the switch points are measured in detail when trolley stops.

